



Error-free model reduction with low-resolution precursor surrogates

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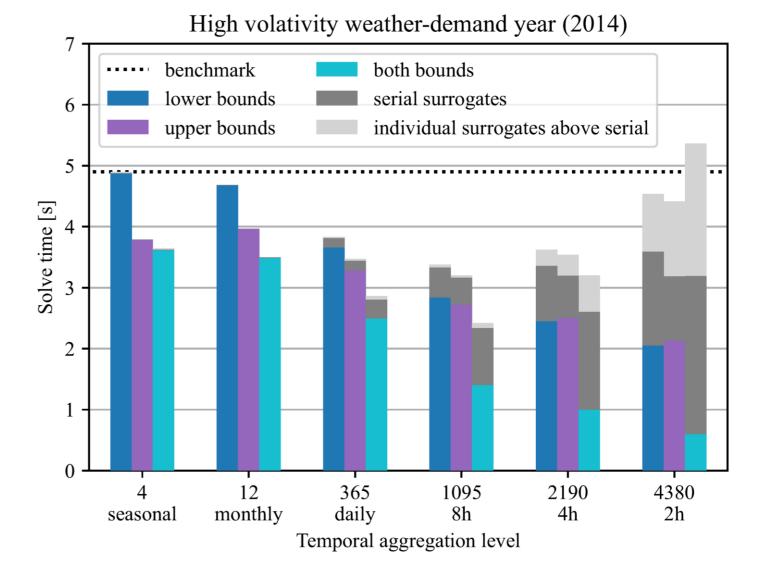
Overcoming the efficiency-accuracy trade-off

- There are "free lunches", big lunches
- Why this is ground-breaking
- How, in short
- More on the way



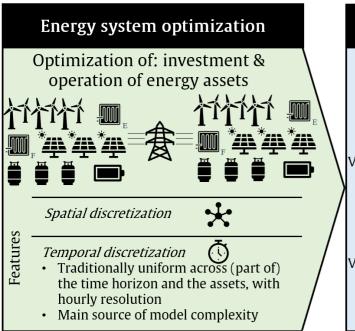
Free, big lunch

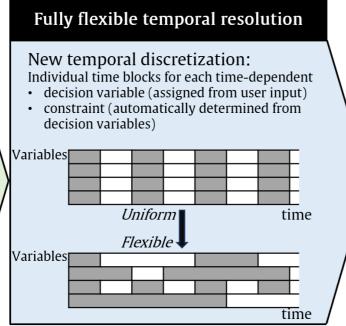
- 100% accuracy, no modeling error.
- Solve time down by
 52%
- or 2.13x speedup

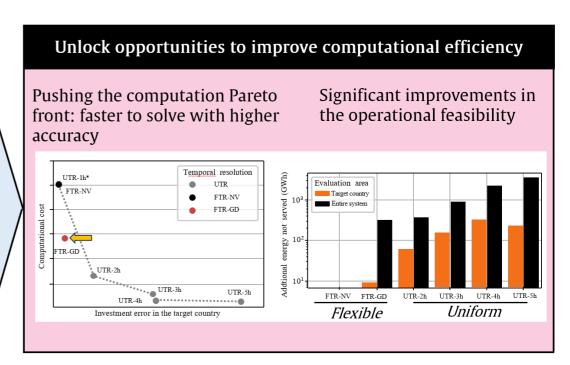




Model reduction comes at the expense of accuracy: Most of the time, also shown in our previous work.





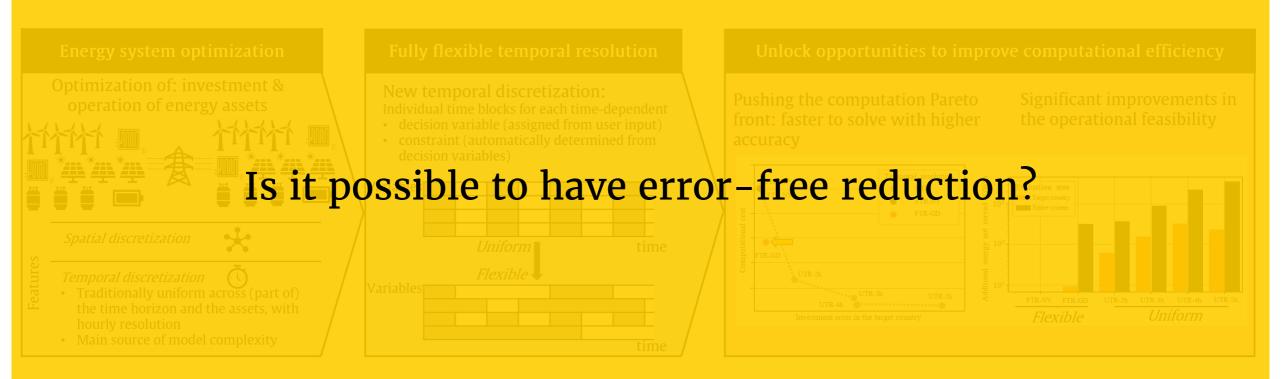


TU Graz Energy System Optimization Workshop

[1] Zhi Gao, Matteo Gazzani, Diego A. Tejada-Arango, Abel Soares Siqueira, Ni Wang, Madeleine Gibescu, Germán Morales-España, Fully flexible temporal resolution for energy system optimization, Applied Energy, Volume 396, 2025, 126267, ISSN 0306-2619, https://doi.org/10.1016/j.apenergy.2025.126267.



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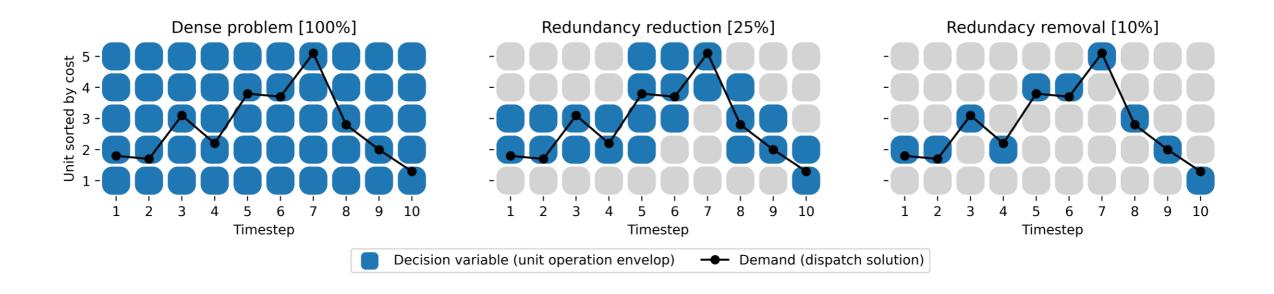


[1] Zhi Gao, Matteo Gazzani, Diego A. Tejada-Arango, Abel Soares Siqueira, Ni Wang, Madeleine Gibescu, Germán Morales-España, Fully flexible temporal resolution for energy system optimization, Applied Energy, Volume 396, 2025, 126267, ISSN 0306-2619, https://doi.org/10.1016/j.apenergy.2025.126267.



Yes! If we can reduce "redundant" variables.

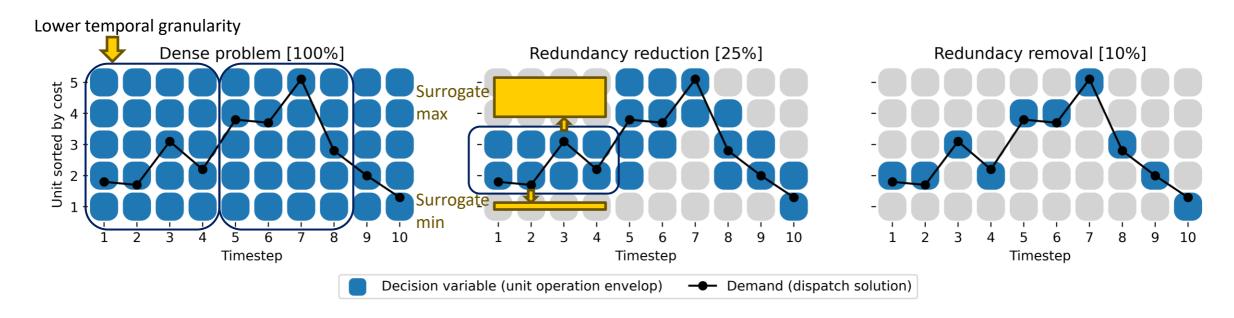
Demonstration with a dispatch problem:
 5 production unit satisfying time-varying demand





Yes! If we can reduce "redundant" variables.

- Demonstration with a dispatch problem:
 5 production unit satisfying time-varying demand
- Low-resolution surrogates examine the best/worst scenario in each window. Variables outside of the boundaries can therefore be removed error-free.
- Similar logic when we have variable availability (like VREnewables).





Mathematical formulation

Economic dispatch of national energy systems

 Surrogates are created in lower resolution, and min/max values of demand and capacity.

$$(P)(\mathbf{b}, \mathbf{e}, \mathcal{T}) : \min \sum_{t \in \mathcal{T}} \sum_{u \in \mathcal{U}} \sum_{n \in \mathcal{N}(u)} c_n x_{t,u,n} \qquad \text{(1a)}$$

$$s.t. \sum_{n \in \mathcal{N}(u)} x_{t,u,n} = b_{t,u} \quad \forall t \in \mathcal{T}, u \in \mathcal{U} \qquad \text{Energy balance of country u}$$

$$x_{t,u,n} \leq e_{t,u,n} \quad \forall t \in \mathcal{T}, u \in \mathcal{U}, n \in \mathcal{N}(u) \qquad \text{Capacity constraint of generator n}$$

where $x_{t,u,n}, e_{t,u,n}, c_n \in \mathbb{R}_{\geq 0}, b_{t,u} \in \mathbb{R}_{\geq 0} \ \forall t \in \mathcal{T}.$



Preservation of accuracy (error-free)

Mathematical proof led by Maaike Elgersma from TU Delft.

Theorem 1. Consider the LP $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$ as defined in (1). We also consider $(P)(\mathbf{b}, \overline{\mathbf{e}}, \mathcal{T})$ and $(\overline{P})(\overline{\mathbf{b}}, \mathbf{e}, \mathcal{T})$, where

$$\overline{\mathbf{b}} \in [\mathbf{b}, \infty), \underline{\mathbf{b}} \in [0, \mathbf{b}], \overline{\mathbf{e}} \in [\mathbf{e}, \infty), \underline{\mathbf{e}} \in [0, \mathbf{e}].$$
 (4)

If $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$, $(\underline{P})(\underline{\mathbf{b}}, \overline{\mathbf{e}}, \mathcal{T})$ and $(\overline{P})(\overline{\mathbf{b}}, \underline{\mathbf{e}}, \mathcal{T})$ are feasible, and $c_i \neq c_j \ \forall i, j \in \mathcal{N}$ where $i \neq j$, then for any optimal solutions $\underline{\mathbf{x}}$ and $\overline{\mathbf{x}}$ to $(\underline{P})(\underline{\mathbf{b}}, \overline{\mathbf{e}}, \mathcal{T})$ and $(\overline{P})(\overline{\mathbf{b}}, \underline{\mathbf{e}}, \mathcal{T})$, respectively, any optimal solution \mathbf{x}^* to $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$) satisfies

$$\min(\underline{x}_{t,u,n}, e_{t,u,n}) \le x_{t,u,n}^* \quad \forall t \in \mathcal{T}, u \in \mathcal{U}, n \in \mathcal{N}(u) \quad (5)$$

and

$$\overline{x}_{t,u,n} < \underline{e}_{t,u,n} \Rightarrow x_{t,u,n}^* \le \overline{x}_{t,u,n} \quad \forall t \in \mathcal{T}, u \in \mathcal{U}, n \in \mathcal{N}(u).$$
(6)

Proof. Suppose $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$, $(\underline{P})(\underline{\mathbf{b}}, \overline{\mathbf{e}}, \mathcal{T})$ and $(\overline{P})(\overline{\mathbf{b}}, \underline{\mathbf{e}}, \mathcal{T})$ are feasible. Let \mathbf{x}^* , $\underline{\mathbf{x}}$, and $\overline{\mathbf{x}}$ be optimal solutions to these

There must be optimal solutions within the surrogate bounds **Corollary 1.** Consider LP $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$ as defined in (1) and the underestimation surrogate LP $(\underline{S})(\underline{\mathbf{b}}, \overline{\mathbf{e}}, \mathcal{T}')$ as defined in (2) with any subset \mathcal{T}' of time steps \mathcal{T} , where

$$\underline{b}_{k,u} = \min_{t \in \mathcal{S}_k} (b_{t,u}), \ \overline{e}_{k,u,n} = \max_{t \in \mathcal{S}_k} (e_{k,u,n})$$
 (10)

 $\forall k \in \mathcal{T}', u \in \mathcal{U}, n \in \mathcal{N}(U)$. Consider also the overestimation surrogate $LP(\overline{S})(\overline{\mathbf{b}}, \mathbf{e}, \mathcal{T}')$ as defined in (2), where

$$\bar{b}_{k,u} = \max_{t \in \mathcal{S}_k} (b_{t,u}), \ \underline{e}_{k,u,n} = \min_{t \in \mathcal{S}_k} (e_{t,u,n})$$
(11)

 $\forall k \in \mathcal{T}', u \in \mathcal{U}, n \in \mathcal{N}(U).$

If $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$, $(\underline{S})(\underline{\mathbf{b}}, \overline{\mathbf{e}}, \mathcal{T}')$, and $(\overline{S})(\overline{\mathbf{b}}, \underline{\mathbf{e}}, \mathcal{T}')$ are feasible, and $c_i \neq c_j \ \forall i, j \in \mathcal{N}$ where $i \neq j$, then for any optimal solutions $\underline{\mathbf{x}}$ and $\overline{\mathbf{x}}$ to $(\underline{S})(\underline{\mathbf{b}}, \overline{\mathbf{e}}, \mathcal{T}')$ and $(\overline{S})(\overline{\mathbf{b}}, \underline{\mathbf{e}}, \mathcal{T}')$, respectively, any optimal solution \mathbf{x}^* to $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$ satisfies

$$\min(\underline{x}_{k,u,n}, e_{t,u,n}) \le x_{t,u,n}^* \tag{12}$$

 $\forall k \in \mathcal{T}', t \in \mathcal{S}_k, u \in \mathcal{U}, n \in \mathcal{N}(u)$ and

$$\overline{x}_{k,u,n} < \underline{e}_{k,u,n} \Rightarrow x_{t,u,n}^* \le \overline{x}_{k,u,n}, \tag{13}$$

 $\forall k \in \mathcal{T}', t \in \mathcal{S}_k, u \in \mathcal{U}, n \in \mathcal{N}(u).$

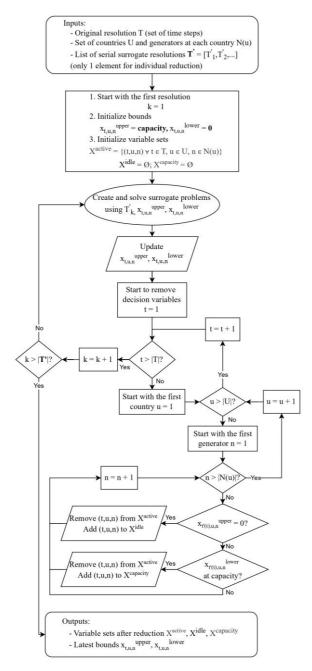
Proof. Suppose $(P)(\mathbf{b}, \mathbf{e}, \mathcal{T})$, $(\underline{S})(\underline{\mathbf{b}}, \overline{\mathbf{e}}, \mathcal{T}')$, and $(\overline{S})(\overline{\mathbf{b}}, \underline{\mathbf{e}}, \mathcal{T}')$ are feasible. We first show that any optimal solutions to



Lowresolution surrogates can be used for this.



Implementation



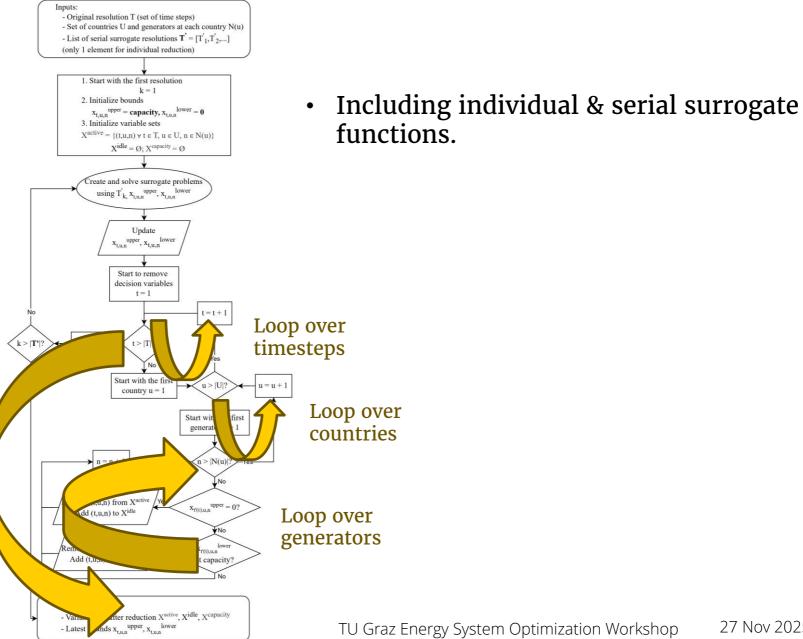
• Including individual & serial surrogate functions.



Implementation

Loop over

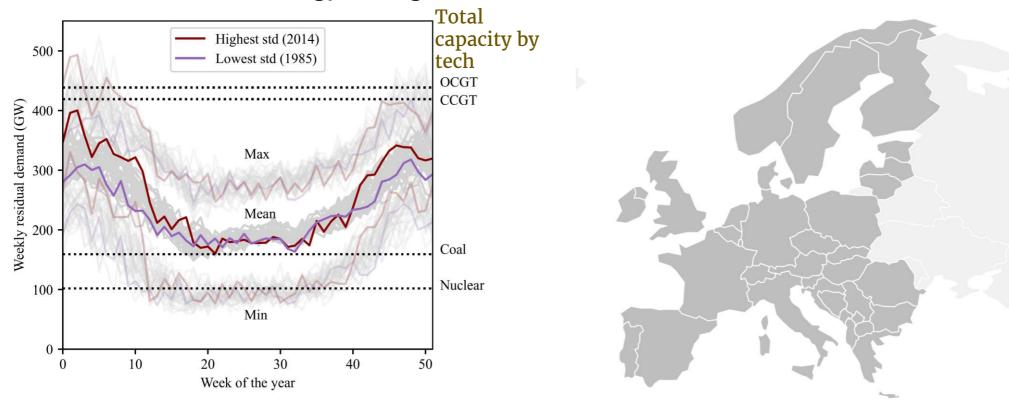
surrogate resolutions





Case study (based on TYNDP 24)

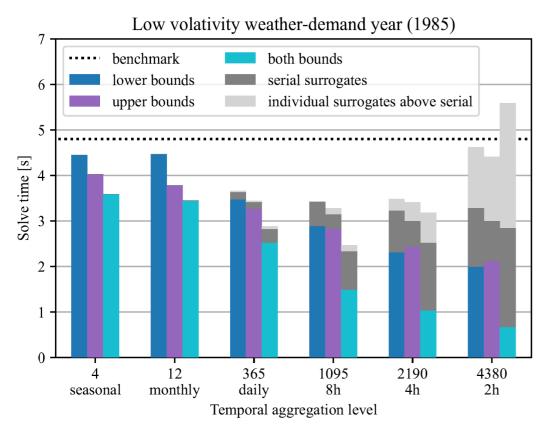
- Economic dispatch of 35 national energy systems.
- Under the most stable and most fluctuating demand-weather years.
- Note: there is no energy storage, no transmission lines.

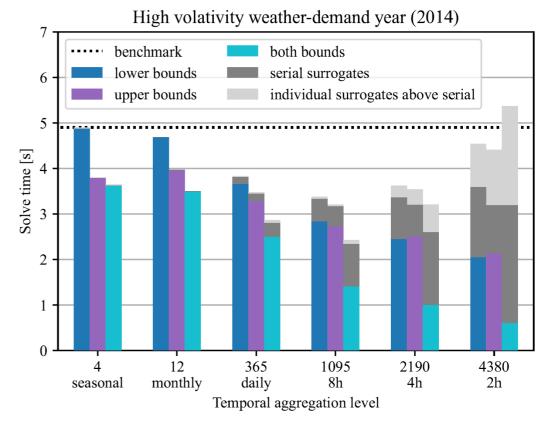




Case study (based on TYNDP 24)

- Significant gains in computational efficiency
- And memory usage (next slide)
- Note again: all instances error-free

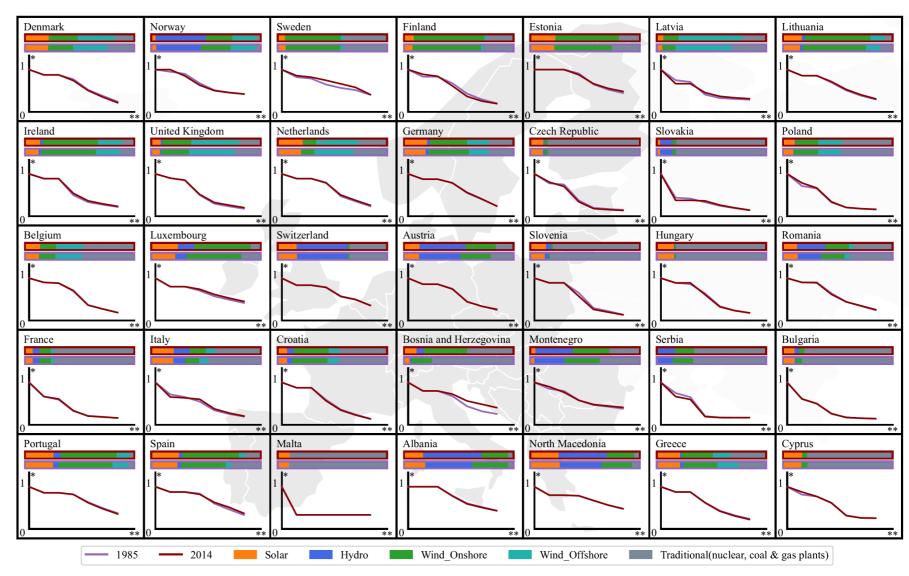






Reduction of decision variables

- Country-country comparison (Estonia & Czech top) (Spain & Malta below)
- Climate year comparison (Bosnia and Herzegovina)





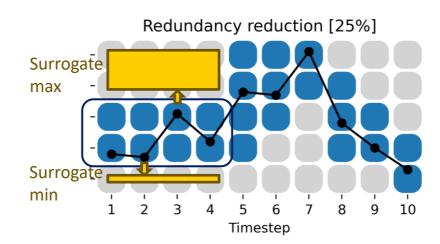
Overcoming the efficiency-accuracy trade-off

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- Why this is ground-breaking
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- More on the way
 - Extend to include more system features (storage, network etc.).
 - Re-think the use of computing power.

Let's keep in touch (Zhi will be open for PostDoc opportunities ⊚)

Zhi Gao, Maaike Elgersma, Madeleine Gibescu, Germán Morales-España, Mathijs de Weerdt, Matteo Gazzani, Error-free model reduction with low-resolution precursor surrogates for energy system optimization. [submitted to PSCC 26]





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